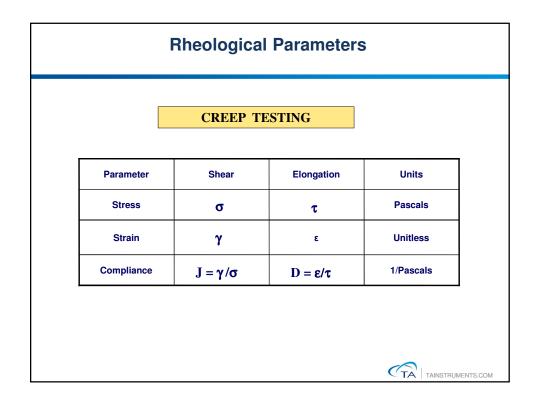
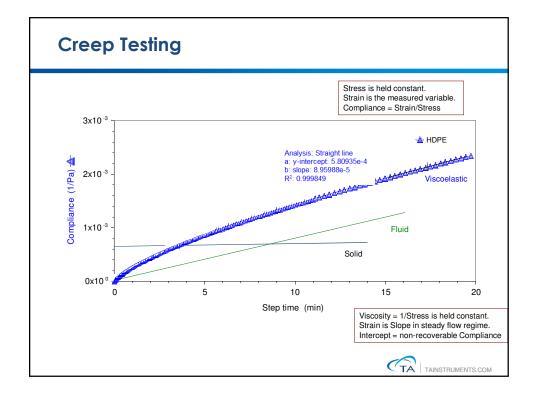
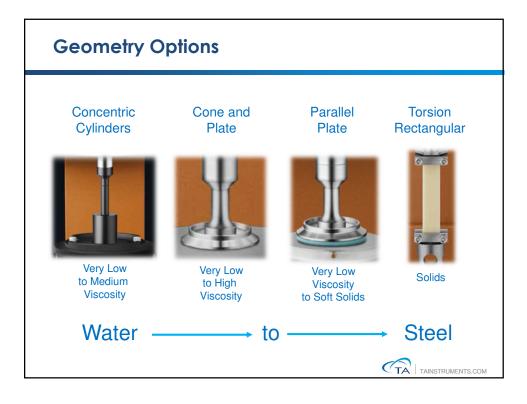


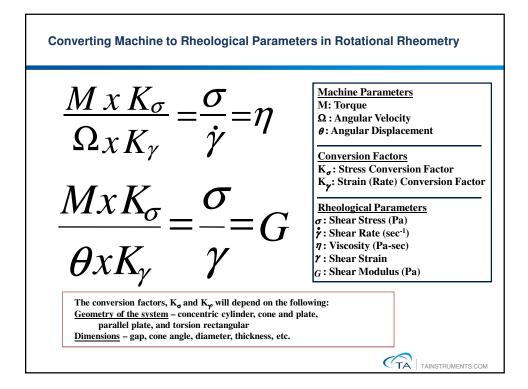
	Rheological Parameters						
	FLUIDS TESTING						
Paramet	er	Shear	Elongation		Units		
Rate		Ϋ́	3		Seconds ⁻¹		
Stress	•	σ	τ		Pascals		
Viscosi	ty η	= σ/γ̀	$\eta_{\rm E} = \tau/\dot{\epsilon}$		Pascal-seconds		
	SOLIDS TESTING						
Parame	ter S	Shear	Elongation		Units		
Strair	1	γ	3		Unitless		
Stress	3	σ	τ		Pascals		
Modulu	ls G(t)	= σ/γ	$E = \tau/\epsilon$		Pascals		
-							

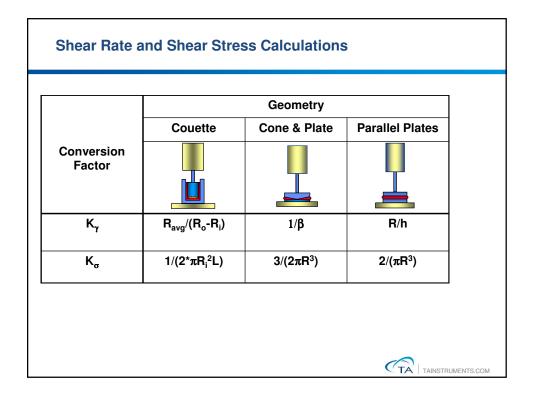


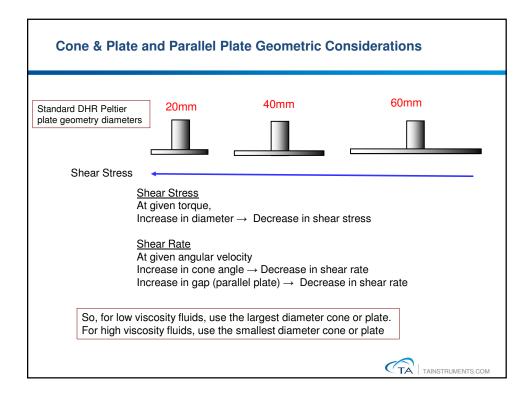


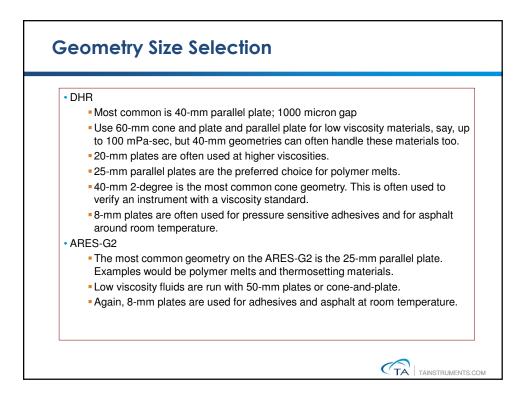


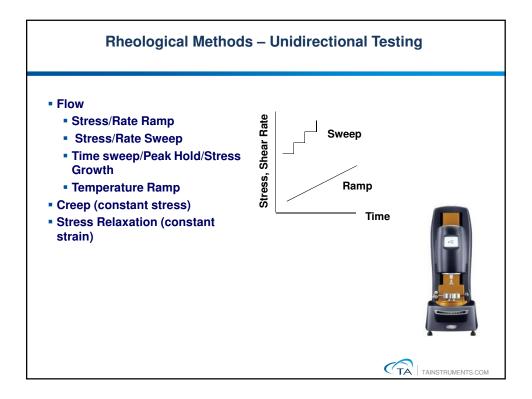
Geometry	Examples
Concentric Cylinder	Coatings Beverages Slurries (vane rotor option) Starch pasting
Cone and Plate	Low viscosity fluids Viscosity standards Sparse materials Polymer melts in steady shear
Parallel Plate	Widest range of materialsAdhesivesPolymer meltsHydrogelsAsphaltCuring of thermosetting materialsFoodsCosmetics
Torsion Rectangular	Thermoplastic solids Thermoset solids

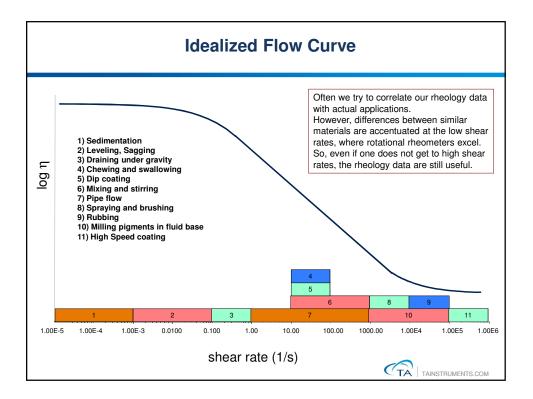


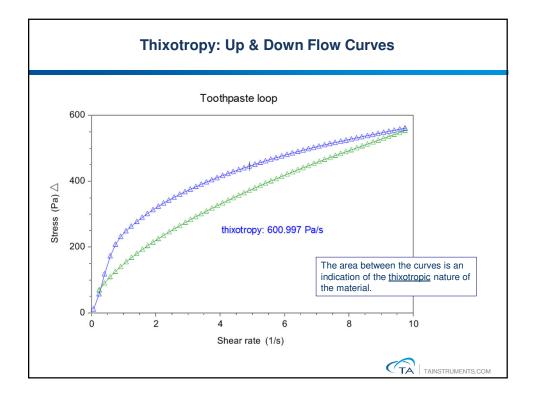


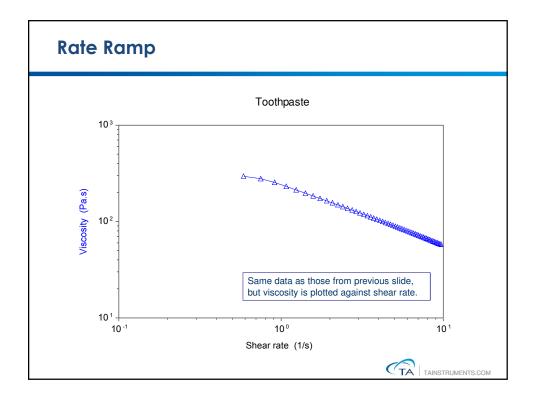


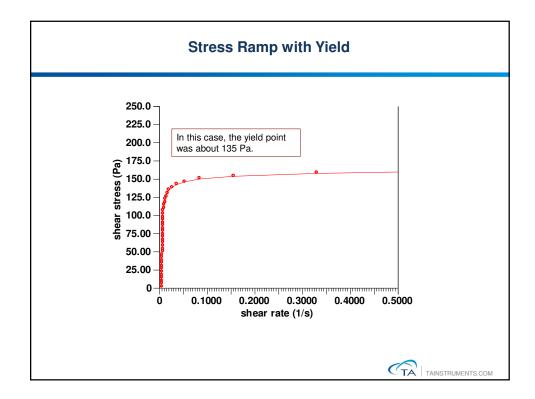


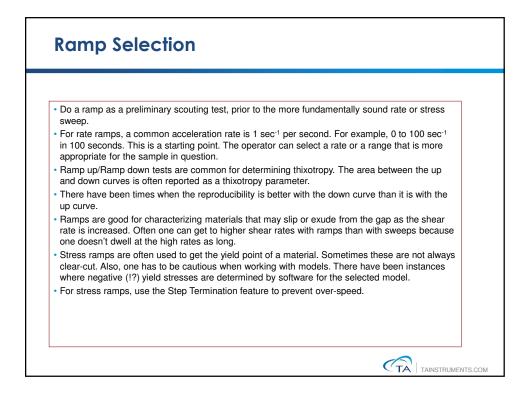


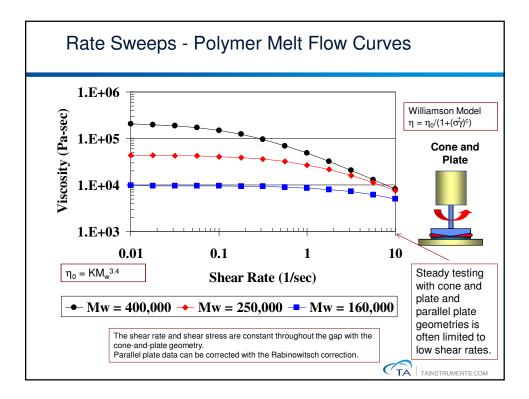


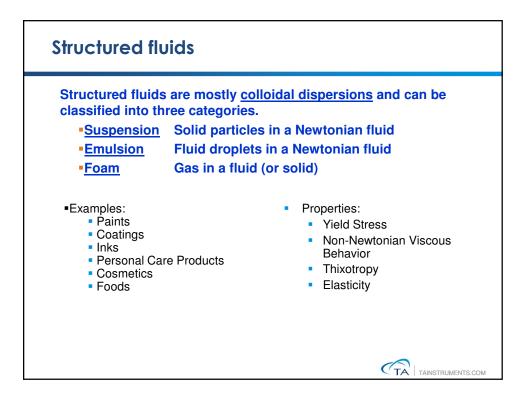


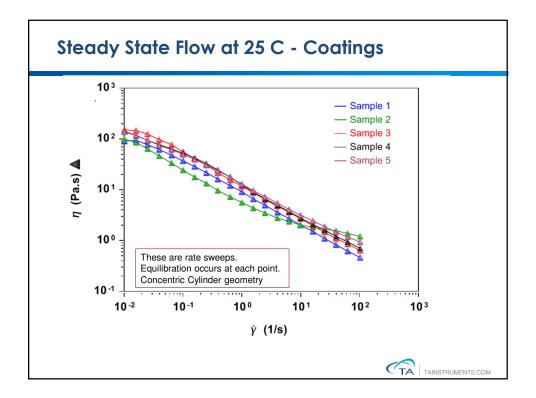


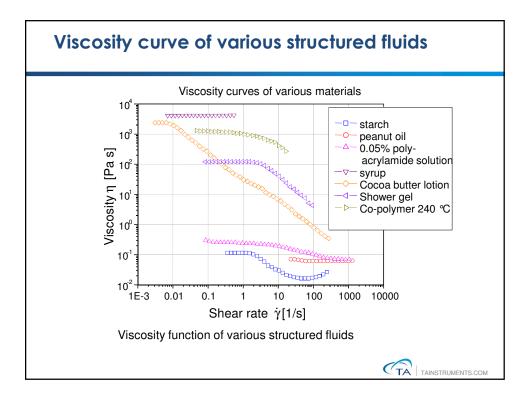


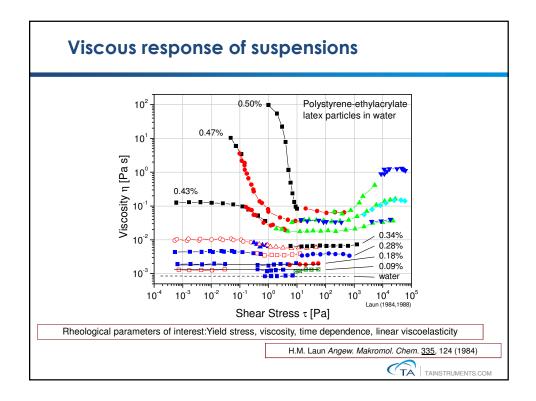


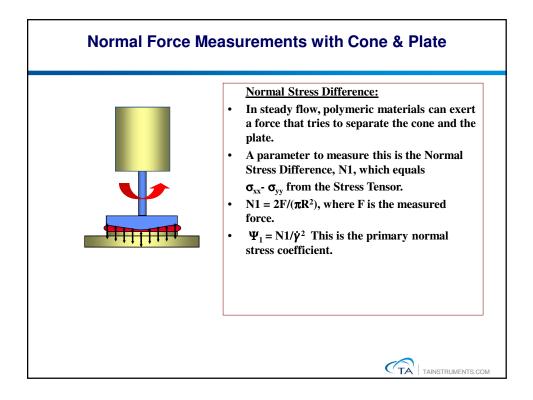


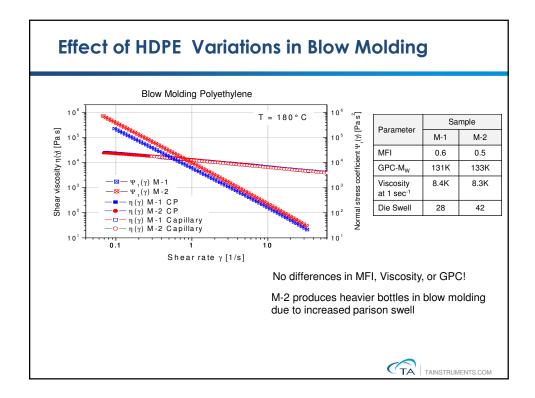


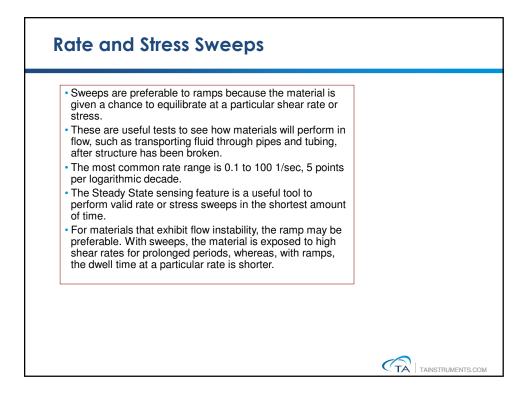


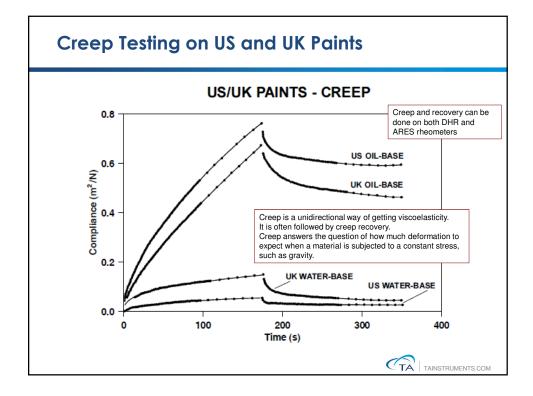


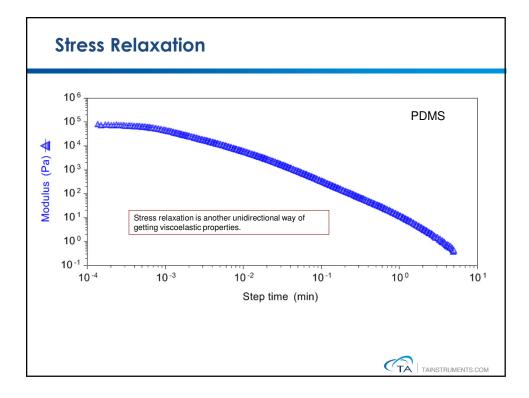


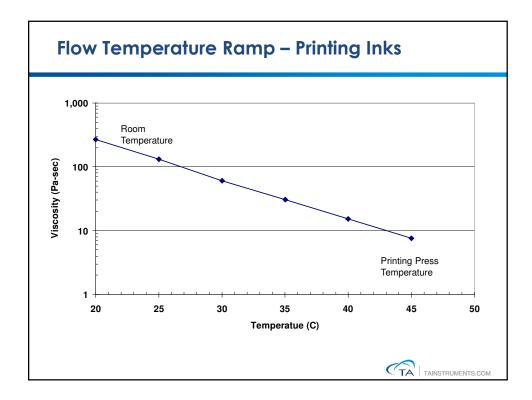


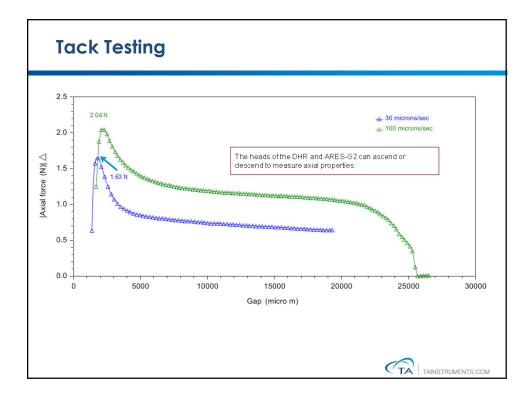


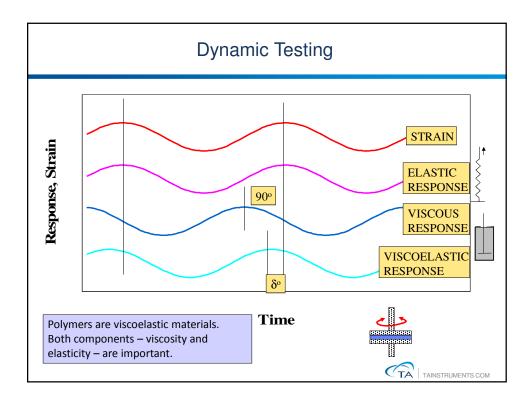




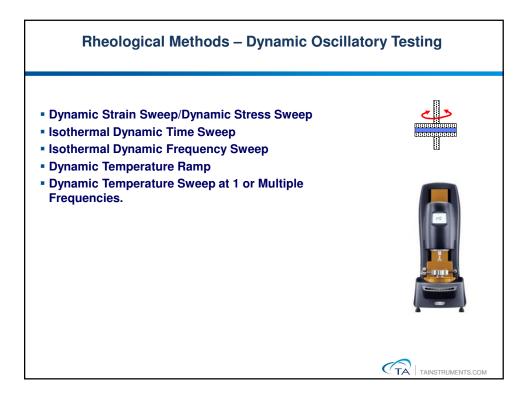


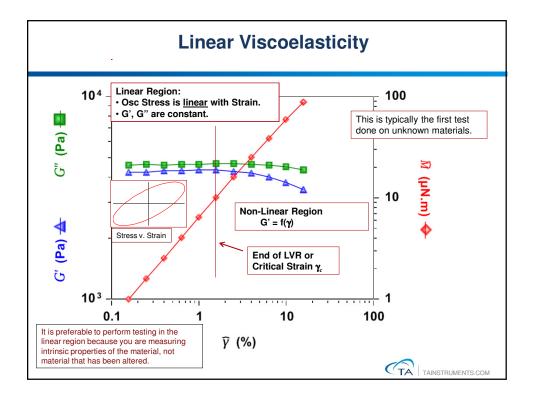


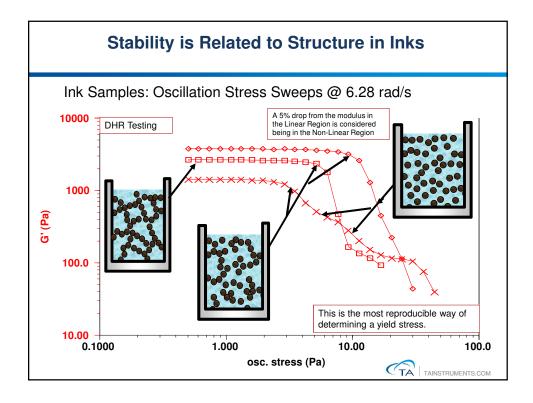


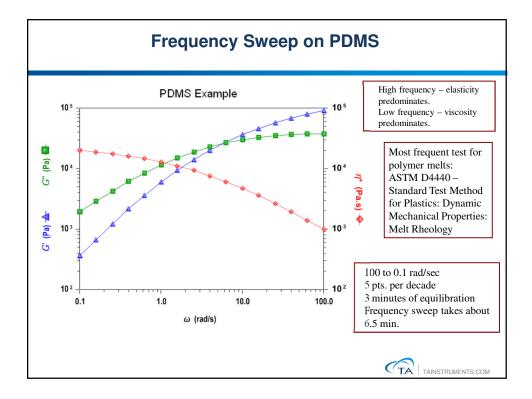


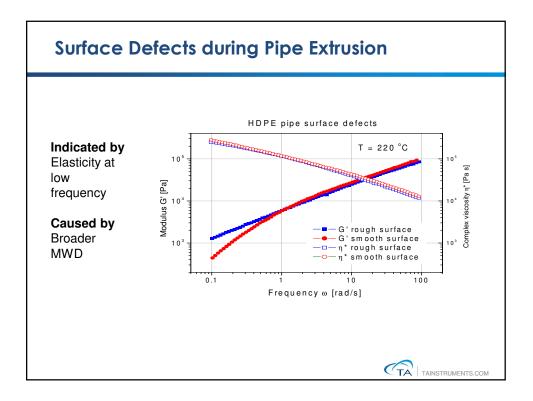
Parameter	Shear	Elongation	Units
Strain	$\gamma = \gamma_0 \sin(\omega t)$	$\varepsilon = \varepsilon_0 \sin(\omega t)$	
Stress	$σ = σ_0 sin(ωt + δ)$	$τ = τ_0 sin(ωt + δ)$	Ра
Storage Modulus (Elasticity)	$G' = (\sigma_0/\gamma_0)cos\delta$	E' = (τ ₀ /ε ₀)cosδ	Ра
Loss Modulus (Viscous Nature)	$G'' = (\sigma_0/\gamma_0) sin\delta$	$E'' = (\tau_0/\epsilon_0) sin \delta$	Pa
Tan δ	G"/G'	E"/E'	
Complex Modulus	G* = (G' ² +G'' ²) ^{0.5}	E* = (E ² +E ²) ^{0.5}	Ра
Complex Viscosity $\eta^* = G^*/\omega$		η _E * = E*/ω	Pa-sec

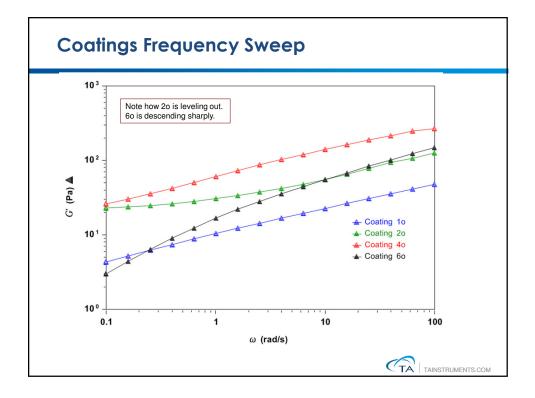


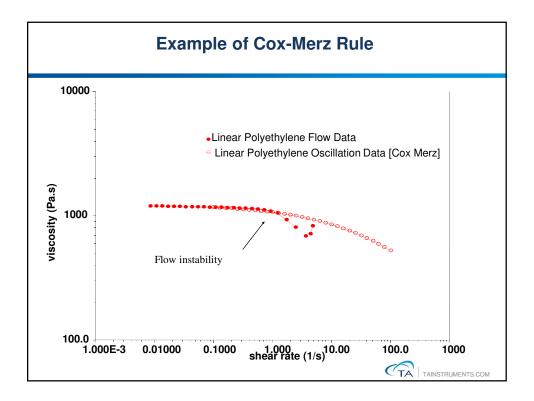


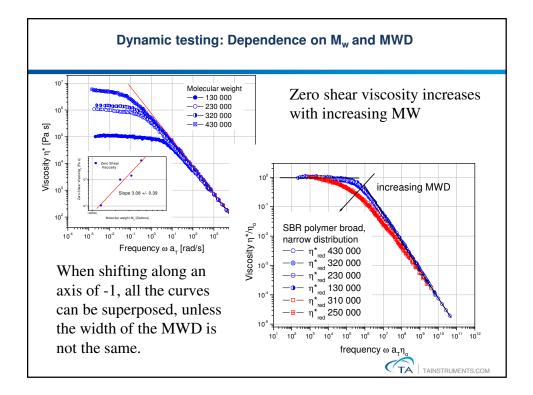


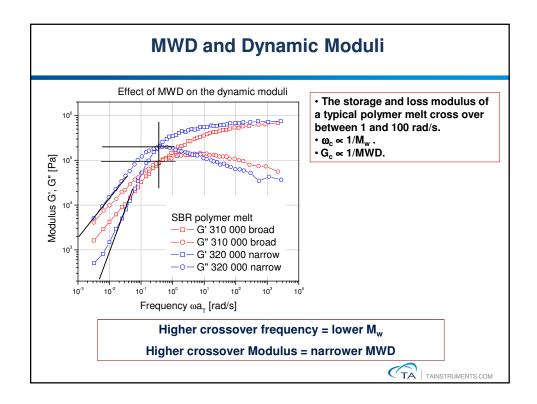


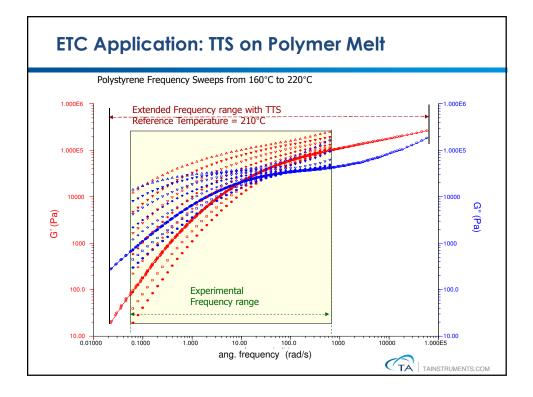


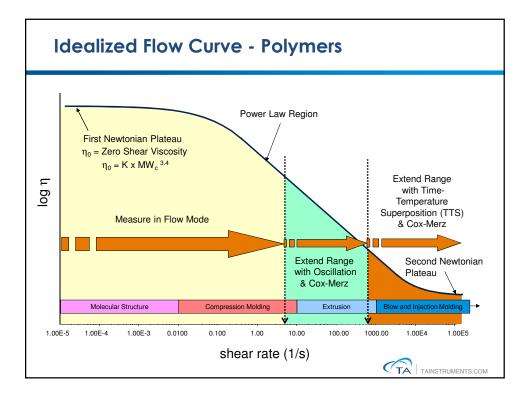


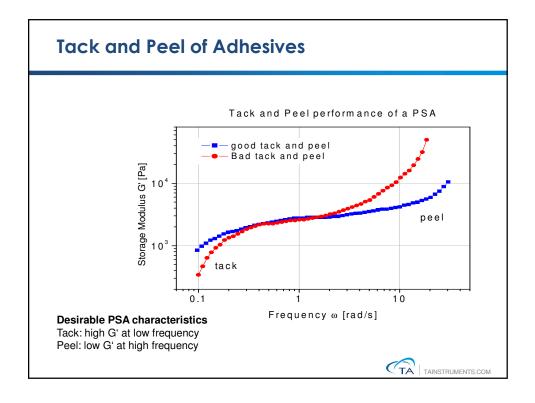




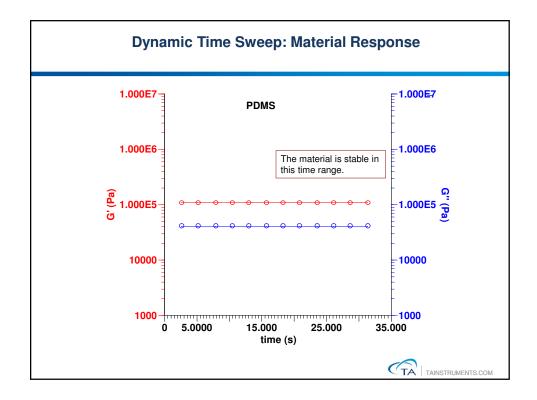


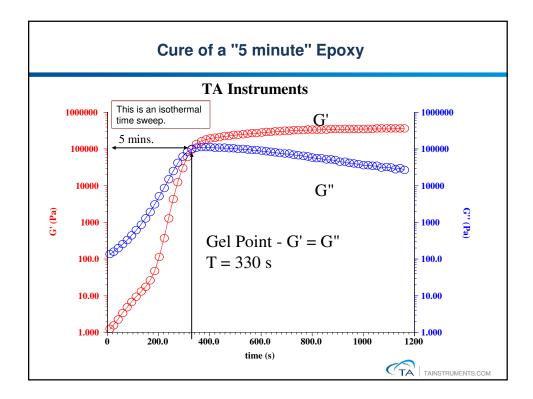


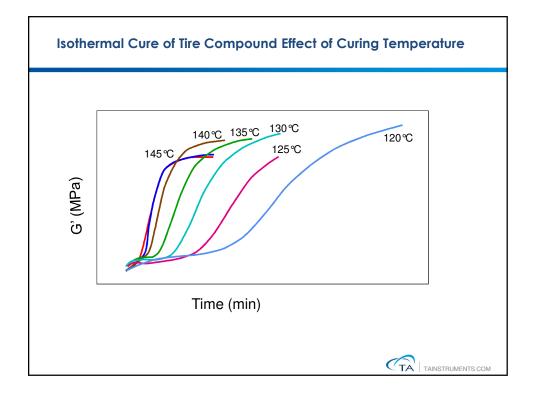


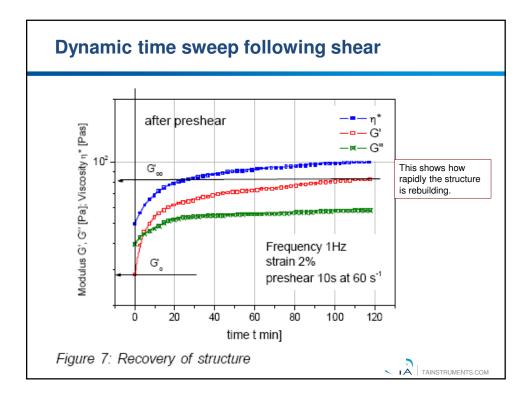


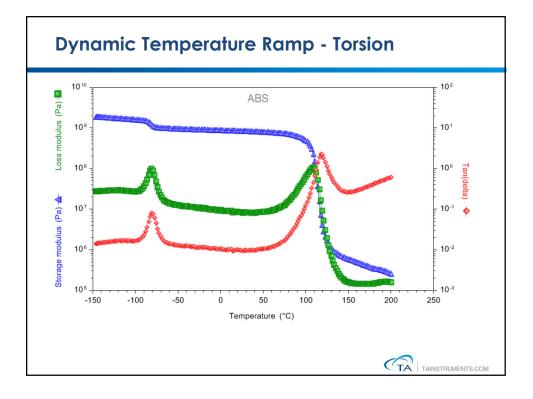
Property	Rheological Properties	Practical Adhesive Property
Tack	 Low tan δ and Low G' Low Cross-links (G" > G' @ ~1 Hz) 	High Tack
Shear Resistance	 High G' @ < 0.1 Hz High Viscosity @ Low Shear Rates 	High Shear Resistance
Peel Strength	• High G" @ ~> 100 Hz	High Peel Strength
Cohesive Strength	 High G', low tan δ 	High Cohesive Strength
Adhesive Strength	 High G", high tan δ 	High Adhesion Strength with Surface

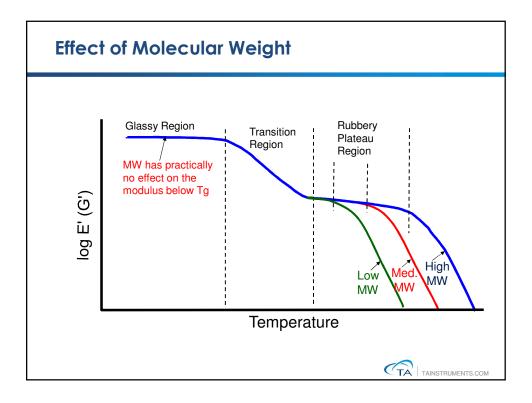


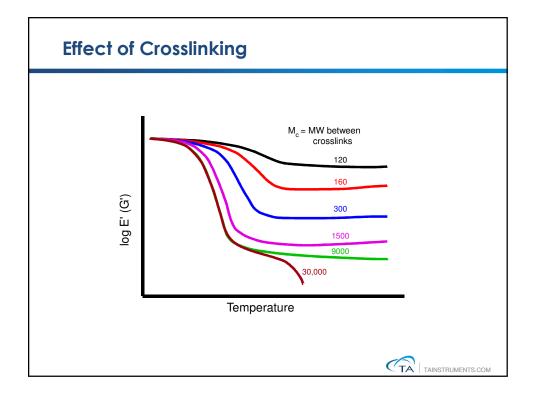


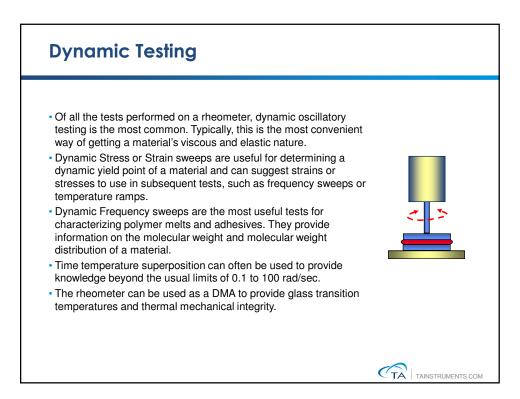


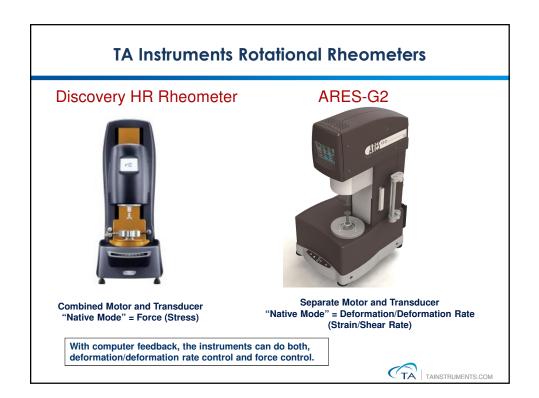




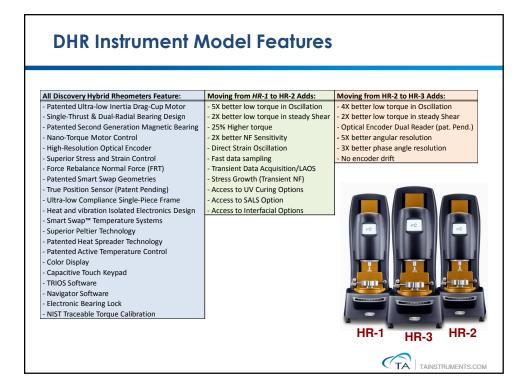








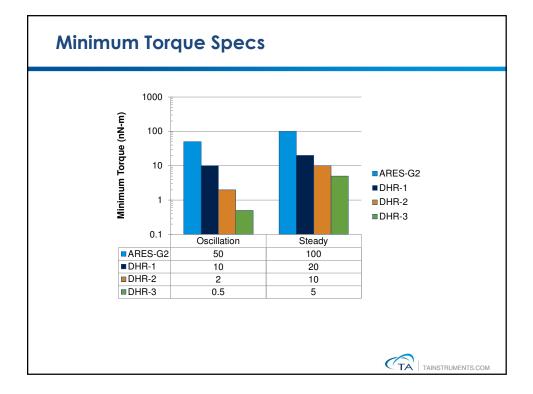
DHR Instrument Specifications						
6	110.0	115.2	115.4	1		
Specification	HR-3	HR-2	HR-1			
Bearing Type, Thrust	Magnetic Porous Carbon	Magnetic Porous Carbon	Magnetic Porous Carbon			
Bearing Type, Radial Motor Design	Drag Cup	Drag Cup	Drag Cup			
Minimum Torque (nN.m) Oscillation	0.5	2	10	HR-1 HR-2 HR-3		
Minimum Torque (nN.m) Steady Shear	5	10	20	HR-I		
Maximum Torque (mN.m)	200	200	150			
Torque Resolution (nN.m)	0.05	0.1	0.1			
Minimum Frequency (Hz)	1.0E-07	1.0E-07	1.0E-07			
Maximum Frequency (Hz)	100	100	100			
Minimum Angular Velocity (rad/s)	0	0	0			
Maximum Angular Velocity (rad/s)	300	300	300			
Displacement Transducer	Optical encoder	Optical encoder	Optical encoder			
Optical Encoder Dual Reader	Standard	N/A	N/A			
Displacement Resolution (nrad)	2	10	10			
Step Time, Strain (ms)	15	15	15			
Step Time, Rate (ms)	5	5	5			
Normal/Axial Force Transducer	FRT	FRT	FRT			
Maximum Normal Force (N)	50	50	50			
Normal Force Sensitivity (N)	0.005	0.005	0.01			
Normal Force Resolution (mN)	0.5	0.5	1			

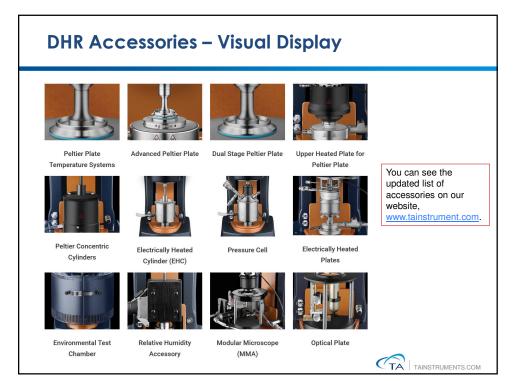


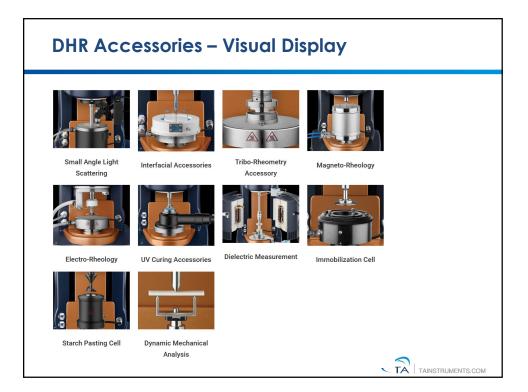
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ARES-G2 Specifications

Force/Torque Rebalance Orthogonal Superposition and DMA modes Transducer (Sample Stress) Motor Control Force Rebalance Transducer Transducer Type Minimum Transducer Force in Force/Torque Rebalance Transducer Torque Motor Brushless DC 0.001 N Oscillation Transducer Normal/Axial Motor Maximum Transducer Force Brushless DC 20 N Minimum Transducer Torque Minimum Displacement in Oscillation 0.5 µm 0.05 uN.m in Oscillation Maximum Displacement in Oscillation 50 µm Minimum Transducer Torque 0.1 µN.m Displacement Resolution 10 nm in Steady Shear Axial Frequency range 1 x 10° Hz to 16 Hz 200 mN.m Maximum Transducer Torque Transducer Torque Resolution 1 nN.m Stepper Motor Transducer Normal/ Movement/Positioning Micro-stepping Motor/ 0.001 to 20 N Axial Force Range Precision Lead Screw Transducer Bearing Groove Compensated Air Position Measurement Linear Optical Encoder Positioning Accuracy 0.1 micron Drive Motor (Sample Deformation) Maximum Motor Torque 800 mN.m Temperature Systems Motor Design Brushless DC Smart Swap Standard Forced Convection Oven, FCO Motor Bearing Jeweled Air, Sapphire -150 °C to 600 °C Optical Encoder Displacement Control/Sensing FCO Camera Viewer Optional -10 °C to 150 °C Strain Resolution 0.04 µrad Advanced Peltier System, APS Min. Angular Displacement 1 urad Pettier Plate -40 °C to 180 °C -10 °C to 150 °C in Oscillation Sealed Bath Max. Angular Displacement Unlimited in Steady Shear Angular Velocity Range 1 x 10^e rad/s to 300 rad/s Angular Frequency Range 1 x 10³ rad/s to 628 rad/s Step Change in Velocity Step Change in Strain 5 ms 10 ms

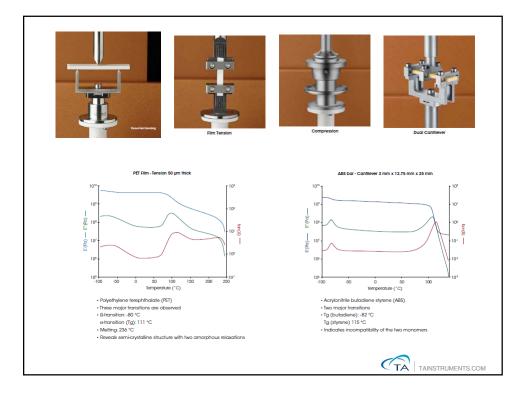




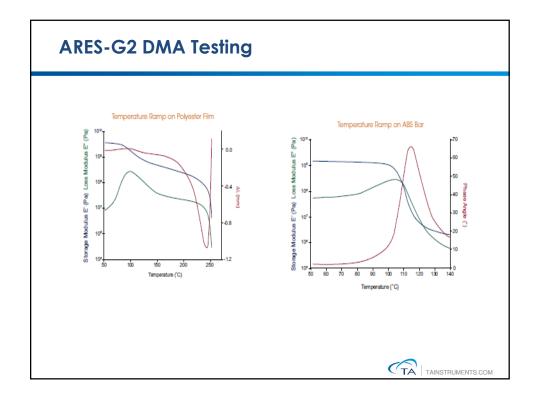




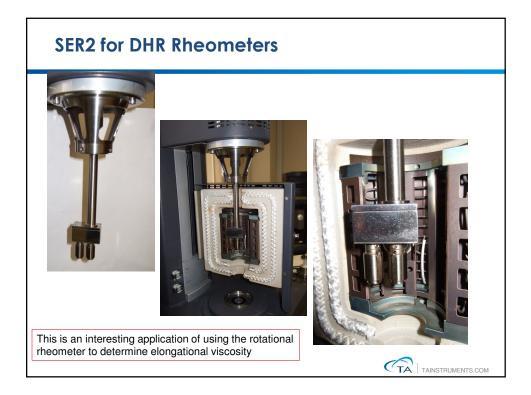
DMA Capabili	ies			
	Motor Control Minimum Force in Oscillation Maximum Axial Force Minimum Displacement in Oscillation Displacement Resolution Axial Frequency Range • DHR Film/Fiber Tension Clamp • DHR 3-Point Bending Clamp Ac • DHR Cantilever Bending Clamp	ccessory kit		
	The DMA capabilities of the DHR and ARES-G2 are unique for commercial rheometers.			

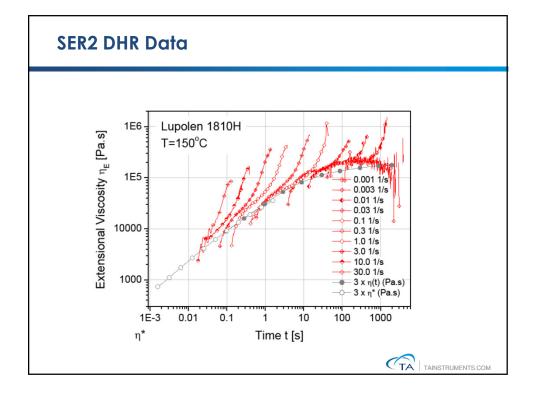


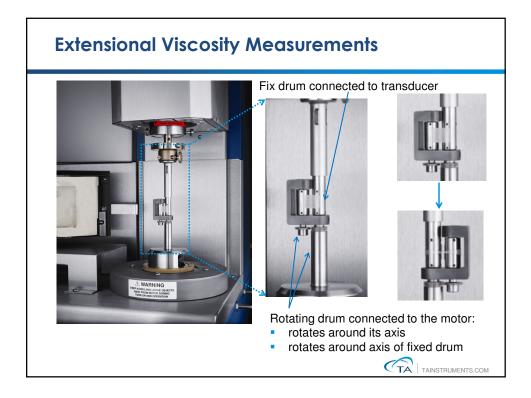


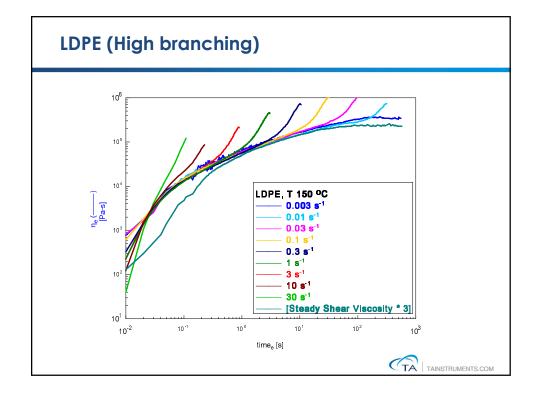


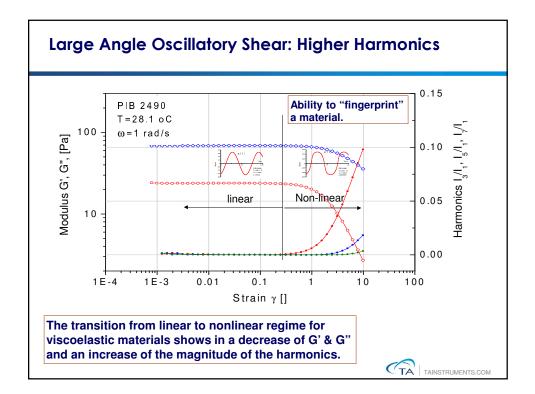
	RSA G2	DMA 850	ARES G2 DMA	DHR DMA (optional)
Max Force	35N	18N	20N	50N
Min Force	0.0005N	0.0001N	0.001N	0.1N
Frequency Range	1e-5 to 628 rad/s (1.6e-6 to 100 Hz)	6.28e-3 to 1250 rad/s (0.001 to 200 Hz)	6.3e ⁻⁵ to 100 rad/s (1.0e ⁻⁵ to 16 Hz)	6.3e ⁻⁵ to 100 rad/s (1.0e ⁻⁵ to 16 Hz)
Dynamic Deformation Range	+/- 0.05 to 1,500µm	+/- 0.005 to 1e4 µm	+/- 1 to 50 µm	+/- 1 to 100 μm
Control Stress/Strain	Control Strain (SMT)	Control Stress (CMT)	Control Strain (CMT)	Control Stress (CMT)
Heating Rate	0.1°C to 60°C/min	0.1°C to 20°C/min	0.1°C to 60°C/min	0.1°C to 60°C/mir
Cooling Rate	0.1°C to 60°C/min	0.1°C to 20°C/min	0.1°C to 60°C/min	0.1°C to 60°C/mir

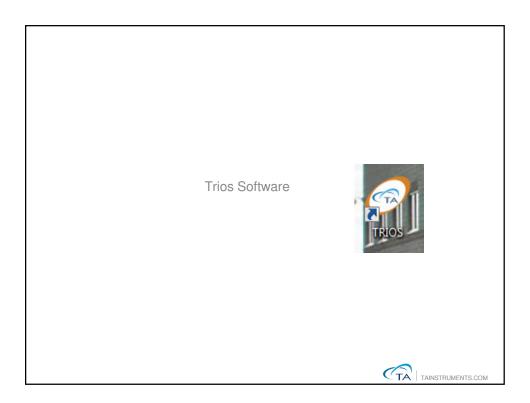


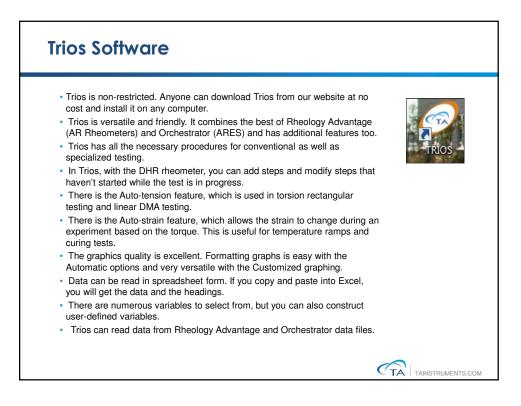




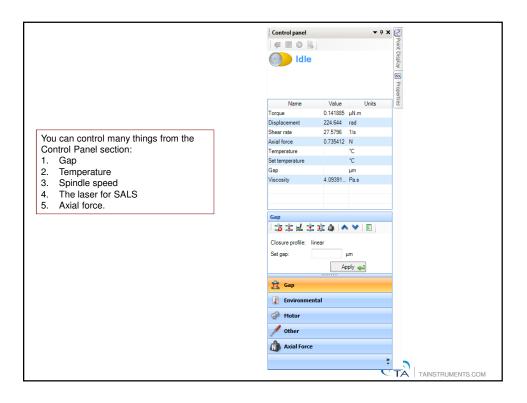




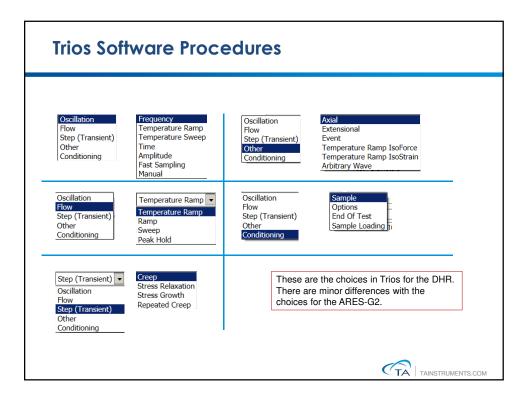




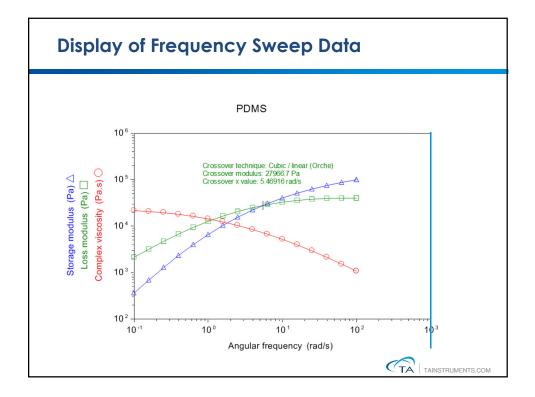
Trios Screen	
Competiment Scripting Instrument Engineering ScriptButons	Offine-Discovery HR-3 : TA Instruments Trics v4 3.0 38388
File Manager	• 9 [Experiment 2]
Image: Contract of the second seco	* Sample: 5600 * Geometry: 40mm 2.0° cone plate, Peltier plate Steel * Procedure: Field Service Test - stress ramp on \$600 procedure * Ø
The Control Panel is shown on the next slide.	1: Flow Ramo 25°C, 00:03:00hh/mm:ss. 0 to final 5000uN m
	ilog 🗸 4
Experiments	Search: Day: Today • Instrument <all> • 🖶</all>
I Results L Geometries Ø Calibration	
E Scripts	



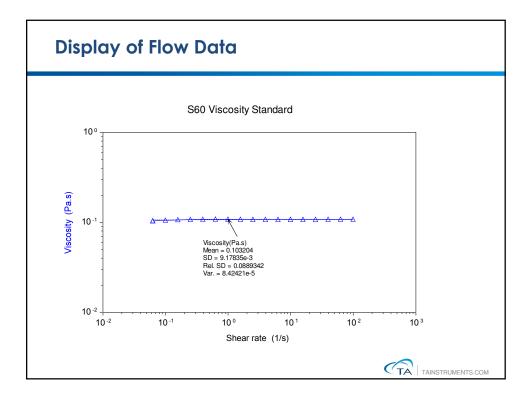
Geometry In	formation	n	
🔶 Geometry: 40mm p	arallel plate, Peltier plate S	Steel	
Diameter Gap Loading gap Trim gap offset	40 mm 1.0 mm 45.0 mm 0.05 mm	file. scar	information will be stored with the geometry t will be accessed when the magnetic reader s the magnetic strip at the top of the netry.
Minimum sample	Steel volume is 1.25664 cm ³		There is a friendly Geometry wizard that guides you through preparing a new geometry.
	re compensation		
Expansion coef	ficient 0.6	µm/°C	Double-pressing the Bearing Lock icon on the touch-pad and loading the geometry in
Compliance Geometry inertia	1.58	mrad/N.m µN.m.s²	the same location. enables you to retain at least most of the mapping
Friction	0.897	μN.m/(rad/s)	✓ Enabled
Stress constant Strain constant	79577.5 20.0	Pa/N.m 1/rad	
Normal stress co Fluid density cor		Pa/N	

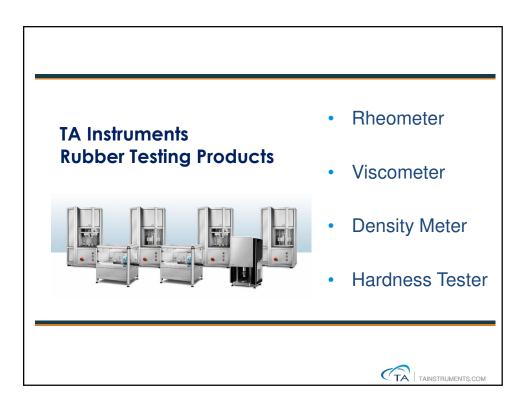


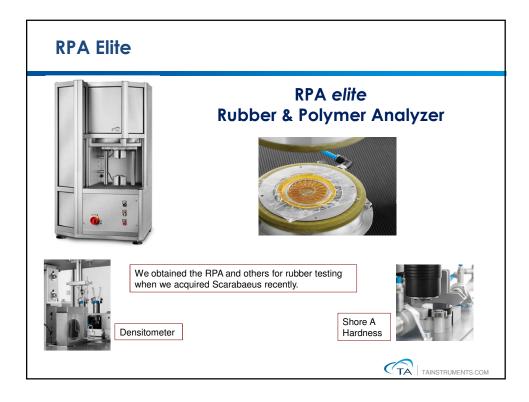
Oscillation P	rocedure		
* Procedure: Sample Frequency	Sweep	\$ 💋 📮 A	1. #
1: Oscillation Free Environmental Control Temperature Soak Time Test Parameters Strain %	25 °C 00:03:00 hh:mm:ss	Vait For Temperature	
Logarithmic sweep Angular frequency Points per decade	100.0 to 0.1	rad/s	

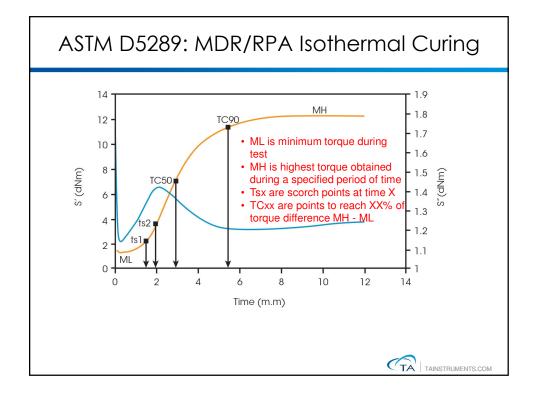


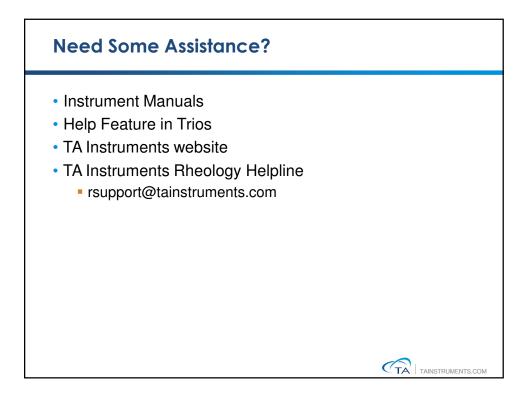
Flow Procedure	
▲ 1: Flow Sweep	
Environmental Control Temperature 25 °C Inherit Set Point	
Temperature 25 °C Inherit Set Point Soak Time 00:03:00 hh:mm:ss V wait For Temperature	
Test Parameters	
Logarithmic sweep	
Shear rate 0.1 to 100.0 1/s -	
Points per decade 5	
Steady state sensing	
Max. equilibration time 00:01:00 hh:mm:ss	
Sample period 00:00:05 hh:mm:ss	
% tolerance 5.0	
Consecutive within 3	
Scaled time average	
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Service Support	Application Support	Software Downloads & Support	Support Plans
Service Support Helpline Site Preparation Guides The IQ/OQ Product Offering Calibration with Certified Standards Safety Data Sheets Supported Instruments Service Shop	Applications Support Helpline Tech Tips Applications Notes Library Training	Software Downloads Instruments sorted by software Software Sorted by Instruments Report a Bug Request a Feature	Lifetime Support Plan Premium Support Plan Plus Support Plan Basic Support Plan Performance Maintenance Visit (PMV) Academic Support Plan ElectroForce Support Plans

